Yaw factor and derived
$|R(\psi, \dot{\delta})|$
$|\tau(\dot{\psi}, \dot{\delta})|$
$|R(\dot{\psi}, \dot{\delta})|$
$|\tau\ (\dot{\psi}, \delta)|$
$H(YF)$
$\sigma(YF)$
$|R(\dot{\psi}, \delta)|$
−0.15 −0.10 0.00 0.10 0.15
$sign(R).R^2$

Mozzi axis
$N_{peaks}(y_{Mozzi})/T$
$H(\theta_{Mozzi})$
$\sigma(\theta_{Mozzi})$
$H(y_{Mozzi})$
all
$v < 2.5m/s$
$v > 2.5m/s$
−0.15 −0.10 0.00 0.10 0.15
$sign(R).R^2$

State variable variability
$\sigma(\dot{\delta})$
$H(\delta)$
$H(\dot{\delta})$
$\sigma(\delta)$
$\sigma(\psi)$
$\sigma(\phi)$
$H(\phi)$
$H(\dot{\phi})$
$\sigma(\dot{\psi})$
−0.15 −0.10 0.00 0.10 0.15
$sign(R).R^2$

Steer into the lean strategy
$|R(\dot{\delta}, \phi)|$
$|\tau\ (\dot{\delta}, \dot{\phi})|$
$|R(\dot{\phi}, \delta)|$
$|R(\dot{\delta}, \dot{\phi})|$
$|\tau(\delta, \phi)|$
$\mu(SST)$
$\sigma(SST)$
$|\tau\ (\dot{\delta}, \phi)|$
$|R(\delta, \phi)|$
$max(SST)$
$|\tau\ (\dot{\phi}, \delta)|$
−0.15 −0.10 0.00 0.10 0.15
$sign(R).R^2$